

# Team 1923: The MidKnight Inventors

Programming Subteam October 24<sup>th</sup>, 2016



### Overview



- Yearly Schedule
- Our Tools
- Activity!
- Q&A



#### Preseason



- Learn Java!
  - Class signups coming out soon!
- Tinker with sensors & test code
  - Using our past seasons' robots
  - Work with fall project robots as they are completed
- Set up GitHub



### Week I - 3



- Before encoders:
  - Plan autonomous
  - Make basic teleop code & dead-reckoning autonomous
  - Determine sensor use for robot systems
- After encoders:
  - Make drive code with encoders
  - Integrate any other sensors
  - Start coding autonomous modes & any teleop automation that may be needed!

### Week 4 - 6



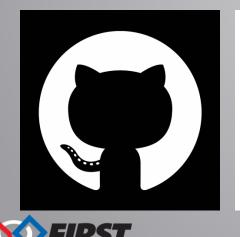
- Program the mechanisms
  - Arms, intakes, shooters, etc
  - Integrate sensors
  - Sequential actions & automation
- Advanced Autons
  - Make use of all available sensors
  - Vision Tracking

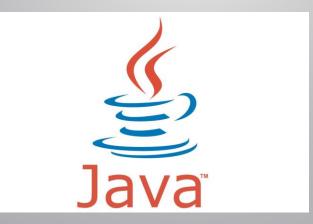


### Technical Stuff



- Language: Java
- IDE: Eclipse
- Github: <a href="https://github.com/Team1923">https://github.com/Team1923</a>





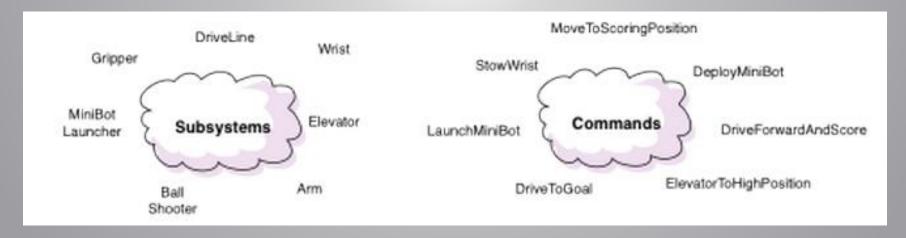


# Command Based Programming



- Subsystems
- Commands
- Command Groups

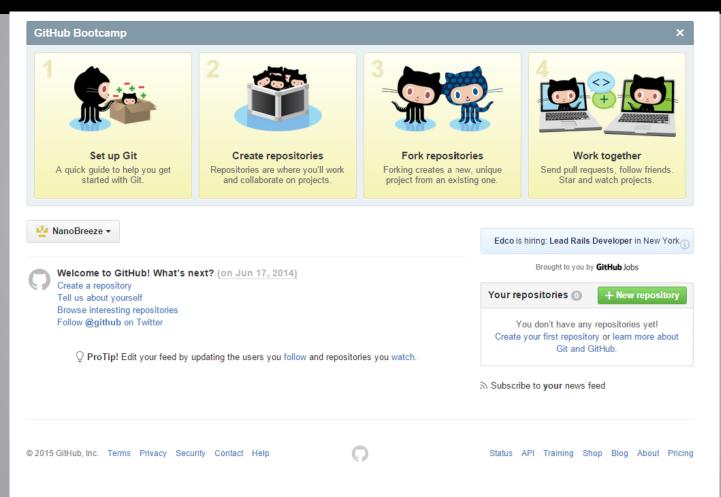






### Github







## Vision Processing







#### Kahoot!



- This brief jeopardy style interactive platform will introduce you to what the programming subteam is all about.
- Kahoot!





### Questions?

